Amendments to the Claims

1. (cancelled)

2. (cancelled)

3. (currently amended) An apparatus for positioning at least one medical treatment device or treatment supporting device by a transportation means to move said device to a predetermined position, wherein said transportation means includes a movable vehicle on which said device is positioned and an automatically guided transport system, and wherein said automatically guided transport system comprises at least one of the following navigation systems:

- an optical tracking navigation system;
- a laser navigation system;
- a magnetic navigation system;
- an inductive guidance navigation system.

4. (previously amended) The apparatus as set forth in claim 3, wherein said device is a nuclear spin tomograph.

5. (original) The apparatus as set forth in claim 4, wherein said nuclear spin tomographic device comprises super-conductive coils of a magnetic flux density of approximately 0.5 Tesla.

6. (previously amended) The apparatus as set forth in claim 3, wherein said device is one of the following:

- a device related to computer tomography;
- an x-ray bow;
- a microscope;
- an operating table;
- a surgeon's stool;
- a treatment navigation device;
- an anesthesia-related device;
- a vehicle for accessories;
- an autoclave device;
- a patient-supervising monitor;

- a sterile material.

7. (currently amended) The apparatus as set forth in claim ~~2~~ 3, wherein said transport system includes a control unit carried by said vehicle, and said control unit includes a radio or wire interface for external control.

9. (currently amended) A method for positioning at least one medical treatment device or treatment supporting device, said device being moved to a predetermined position by a transportation means including a movable vehicle on which the device is carried, wherein said transportation means is controlled by an automatically guided transport system; and wherein said automatically guided transport system uses at least one of the following navigation systems for steering purposes:

- an optical tracking navigation system;
- a laser navigation system;
- a magnetic navigation system;
- an inductive guidance navigation system.

10. (previously amended) The method as set forth in claim 9, wherein a mobile nuclear spin tomographic device is transported.

11. (previously amended) The method as set forth in claim 9, wherein one of the following devices is being transported:

- a device related to computer tomography;
- an x-ray bow;
- a microscope, particularly a surgical microscope;
- an operating table;
- a surgeon's stool;
- a treatment navigation device;
- an anesthesia-related device;
- a vehicle for accessories;
- an autoclave device;
- a patient-supervising monitor;
- a sterile material.

12. (currently amended) The method as set forth in 9, wherein ~~said device is carried on a vehicle,~~ said transport system is provided on said vehicle and is externally activated via a radio or wire interface.

15. (currently amended) An apparatus for positioning at least one medical treatment device or treatment supporting device by a transportation means to move said device to a predetermined position, wherein said transportation means includes an automatically guided transport system, and wherein said automatically guided transport system comprises [The apparatus as set forth in claim 3, wherein said transport system is] an optical tracking navigation system, and said optical tracking navigation system includes a ground guidance band and an optical sensor for sensing the ground guidance band.

16. (previously added) The apparatus as set forth in claim 15, wherein the optical tracking navigation system includes a path measuring system.

17. (previously added) The apparatus as set forth in claim 3, wherein said transport system is a laser navigation system, and said laser navigation system includes a laser, reflectors and a path measuring system.

18. (currently amended) An apparatus for positioning at least one medical treatment device or treatment supporting device by a transportation means to move said device to a predetermined position, wherein said transportation means includes an automatically guided transport system, and wherein said automatically guided transport system comprises [The apparatus as set forth in claim 3, wherein said transport system is] a magnetic navigation system, and said magnetic navigation system includes a ground floor magnetic track or magnetic strip and a path measuring system.

19. (currently amended) An apparatus for positioning at least one medical treatment device or treatment supporting device by a transportation means to move said device to a predetermined position, wherein said transportation means includes an automatically guided transport system, and wherein said automatically guided transport system comprises [The apparatus as set forth in claim 3, wherein said transport system is] an inductive guidance navigation system, and said inductive guidance navigation system includes a ground guidance wire with a frequency generator, and a steering antenna.

20. (previously added) The apparatus as set forth in claim 19, wherein the inductive guidance navigation system includes a path measuring system.

21. (previously added) The apparatus as set forth in claim 3, wherein said movable vehicle is self-driven.

22. (previously added) The apparatus as set forth in claim 3, wherein the device is an image-generating device.

23. (currently amended) The method as set forth in claim 9, wherein ~~said device is carried on a vehicle, and~~ the vehicle is self-driven.

24. (currently amended) A method for positioning at least one medical treatment device or treatment supporting device, said device being moved to a predetermined position by a transportation means, wherein said transportation means is controlled by an automatically guided transport system; and wherein said automatically guided transport system uses at least one of the following navigation systems for steering purposes:

- an optical tracking navigation system;
- a laser navigation system;
- a magnetic navigation system;
- an inductive guidance navigation system; and

[The method as set forth in claim 9,] wherein said device is moved to a pre-position at a first speed and then moved from the pre-position to an operative position at a slower speed for more precise positioning of the device at the operative position.